

Cauchy problem for the nonlinear Klein-Gordon equation coupled with the Maxwell equation

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Abstract In this paper, we study the nonlinear Klein-Gordon equation coupled with a Maxwell equation. Using the energy method, we obtain a local existence result for the Cauchy problem.

Key words: Klein-Gordon-Maxwell system, Cauchy problem, symmetric hyperbolic system, energy method

I. INTRODUCTION

In this paper, we consider the following nonlinear Klein-Gordon equation coupled with Maxwell equation:

$$\begin{aligned} \psi_{tt} - \Delta\psi &= -2ie\varphi\psi_t - ie\varphi_t\psi + e^2|\varphi|^2\psi - 2ie\nabla\psi \cdot \mathbf{A} \\ &\quad - e^2|\mathbf{A}|^2\psi - ie\psi \operatorname{div}\mathbf{A} - m\psi + W(\psi). \end{aligned} \quad (1.1)$$

$$\mathbf{A}_{tt} - \Delta\mathbf{A} = e\operatorname{Im}(\bar{\psi}\nabla\psi) - e^2|\psi|^2\mathbf{A} - \nabla\varphi_t - \nabla\operatorname{div}\mathbf{A}. \quad (1.2)$$

$$-\Delta\varphi = e\operatorname{Im}(\psi\bar{\psi}_t) - e^2|\psi|^2\varphi + \operatorname{div}\mathbf{A}_t. \quad (1.3)$$

where $\psi : \mathbb{R} \times \mathbb{R}^3 \rightarrow \mathbb{C}$, $\mathbf{A} : \mathbb{R} \times \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $\varphi : \mathbb{R} \times \mathbb{R}^3 \rightarrow \mathbb{R}$, $m > 0$, $e \in \mathbb{R}$ and i denotes the unit complex number, that is, $i^2 = -1$. Moreover, $W(s)$ is a regular real valued function which is extended to the complex plane by setting $W^i(\psi) = W(|\psi|)\frac{\psi}{|\psi|}$ for $\psi \in \mathbb{C}$.

In this system, ψ represents an electrically charged field and (φ, \mathbf{A}) is a gauge potential of an electromagnetic field. System (1.1)-(1.3) describes the interaction of a particle with an electromagnetic field in the following way. On one hand, the field ψ produces a current which acts as a source for the electromagnetic field. On the other hand, the electromagnetic field influences the behavior of the particle through the latter's electric charge. Here the field ψ is interpreted as the quantum wave function of the particle. (See Section 2 for the derivation.) We refer to [14], [16] for more physical backgrounds.

To our knowledge, there are only few results concerning the Cauchy problem associated with System (1.1)-(1.3). In [8], [13], the authors investigate the existence theory for the linear Wave-Maxwell equation, that is for the case $m = 0$ and $W^i = 0$. In [15], existence results for (1.1)-(1.3) are established under several conditions on W . The aim of this paper is to obtain a local existence theory for Equations (1.1)-(1.3) by using a standard energy method and a symmetrization process. Note that global existence cannot be obtained by standard arguments and thus seems out of reach for the moment. However, in this direction, one can look for particular global solutions, such as standing waves of the type:

$$\psi(t, x) = u(x)e^{i\omega t} \quad (\omega \in \mathbb{R}), \quad \mathbf{A}(t, x) = \mathbf{0} \quad \text{and} \quad \varphi(t, x) = \varphi(x). \quad (1.4)$$

Plugging (1.4) into (1.1)-(1.3) leads to the following elliptic system:

$$\begin{aligned} \Delta u + m^2 u - (\omega + e\varphi)^2 u &= W^i(u). \\ -\Delta\varphi + e^2 u^2 \varphi &= -e\omega u^2. \end{aligned} \quad (1.5)$$

The existence of solutions to System (1.5) has been studied widely. (See [2], [3], [7], [9] and references therein.) The stability of standing waves has been also considered in [4], [5], [15]. Especially in [4] and [5], the authors showed that the standing wave is stable when the potential term is *positive*, that is, $\frac{m^2}{2}s^2 - W(s) \geq 0$ for $s \geq 0$. However some challenging problems, for example the (in)stability for large ϵ , are still left open.

System (1.1)-(1.3) has a so-called *gauge ambiguity*, thus we need to choose a suitable gauge condition. In this paper, we impose the Coulomb condition, that is, we look for a solution \mathbf{A} which satisfies

$$\operatorname{div} \mathbf{A} = 0. \tag{1.6}$$

In this setting, one has $|\operatorname{rot} \mathbf{A}|^2 = |\nabla \psi|^2$ which seems to be useful for the stability analysis of the standing wave.

To state our main results, we introduce the following notations. First we impose the following initial conditions at $t = 0$:

$$\begin{cases} \psi(0, x) = \psi_{(0)}(x), & \psi_t(0, x) = \psi_{(1)}(x), \\ \mathbf{A}(0, x) = \mathbf{A}_{(0)}(x), & \mathbf{A}_t(0, x) = \mathbf{A}_{(1)}(x), \\ \operatorname{div} \mathbf{A}_{(0)} = 0, & \operatorname{div} \mathbf{A}_{(1)} = 0. \end{cases} \tag{1.7}$$

Moreover we assume that for some $m \in \mathbb{N}$ with $m \geq 2$,

$$\begin{aligned} \psi_{(0)} &\in H^{m+1}(\mathbb{R}^3, \mathbb{C}), & \psi_{(1)} &\in H^m(\mathbb{R}^3, \mathbb{C}), \\ \mathbf{A}_{(0)} &\in H^{m+1}(\mathbb{R}^3, \mathbb{R}^3) & \text{and } \mathbf{A}_{(1)} &\in H^m(\mathbb{R}^3, \mathbb{R}^3), \end{aligned} \tag{1.8}$$

where $H^m(\mathbb{R}^3, \cdot)$ denotes the usual Sobolev space. We also introduce the space $D^{1,2}(\mathbb{R}^3)$ which denotes the completion of $C_0^\infty(\mathbb{R}^3)$ with respect to the norm: $\|u\|^2 := \int_{\mathbb{R}^3} |\nabla u|^2 dx$. We recall, by the Sobolev inequality, that the space $D^{1,2}(\mathbb{R}^3)$ is continuously embedded into $L^6(\mathbb{R}^3)$.

For the nonlinear term W , we assume that

$$(A) \quad W \in C^{m+1}(\mathbb{C}, \mathbb{C}) \text{ and } W(0) = W'(0) = 0.$$

Some typical examples of the nonlinear term W are the power nonlinearity $W(s) = \pm \frac{1}{p} |s|^p$ with $[p] \geq m + 1$ ($[p]$ denotes the integer part of p), or the *cubic-quintic* nonlinearity $W(s) = \frac{1}{3} s^3 - \frac{\lambda}{5} s^5$ for $\lambda > 0$, which frequently appears in the study of solitons in physical literatures. (See [12], [14], [16] for example.)

In this setting, we have the following result.

Theorem 1.1. *Suppose that (A) holds and $(\psi_{(0)}, \psi_{(1)}, \mathbf{A}_{(0)}, \mathbf{A}_{(1)})$ satisfies (1.8). Then there exists $T^* > 0$ such that System (1.1)-(1.3) with the initial condition (1.7) has a unique solution $(\psi, \mathbf{A}, \varphi)$ satisfying the Coulomb condition (1.6) and*

$$\begin{aligned} \psi &\in C([0, T^*], H^{m+1}) \cap C^1([0, T^*], H^m), \\ \mathbf{A} &\in C([0, T^*], H^{m+1}) \cap C^1([0, T^*], H^m), \\ \varphi &\in C([0, T], D^{1,2}), \quad \nabla \varphi \in C([0, T^*], H^m), \quad \varphi_t \in C([0, T^*], H^m). \end{aligned}$$

In [8], [13], [15], the authors used Strichartz estimates and space time estimates for null forms to obtain a local solution. In this paper, we adopt a different approach. More precisely, we apply the strategy developed in [6] and our proof is based on the standard energy method for symmetric hyperbolic systems. We emphasize that our approach is much elementary. We also expect that our method is applicable for the Cauchy problem associated with the nonlinear Klein-Gordon equation coupled with Born-Infeld equations. (See [10], [18].)

This paper is organized as follows. In Section 2, we introduce the derivation of System (1.1)-(1.3) and exhibit some conservation laws. In Section 3, we give several estimates for the elliptic equation (1.3). We prove Theorem

1.1 in Section 4. Firstly, we rewrite System (1.1)-(1.3) as a symmetric hyperbolic system in Section 4.1. Secondly, in Section 4.2, we prove the existence of a unique local solution by using the energy method.

Notations. In this paper, we use the following notations. Let $\beta = (\beta_1, \beta_2, \beta_3)$ e a multi-index of order $|\beta| = \beta_1 + \beta_2 + \beta_3$ and define

$$D^{\beta}u = \frac{\partial^{|\beta|}u}{\partial x_1^{\beta_1} \partial x_2^{\beta_2} \partial x_3^{\beta_3}}$$

For a non-negative integer s , we denote by $D^s u$ the set of all partial space derivatives of order s .

2 Derivation and conservation laws

In this section, we briefly introduce the derivation of System (1.1)-(1.3) and derive some conservation laws. Now we consider the (complex) nonlinear Klein-Gordon equation:

$$\psi_{tt} - \Delta\psi = -m^2\psi + W'(\psi)$$

and the corresponding Lagrangian:

$$L_1 = \frac{1}{2} |\psi_t|^2 - |\nabla\psi|^2 - m^2|\psi|^2 + W(\psi) = -\frac{1}{2} \partial_\alpha \bar{\psi} \partial^\alpha \psi + m^2|\psi|^2 + W(\psi), \tag{2.1}$$

where $\partial_\alpha = \frac{\partial}{\partial x_\alpha}$, $\alpha = 0, 1, 2, 3$ and $x_0 = t$.

Suppose that ψ is an electrically charged field. Then ψ must interact with the Maxwell field. Let \mathbf{E} and \mathbf{H} be the electric and the magnetic fields respectively, and assume that they are described by the Gauge potential (φ, \mathbf{A}) , $\mathbf{A} = (A_1, A_2, A_3)$ as follows:

$$\mathbf{E} = \nabla\varphi + \mathbf{A}_t \quad \text{and} \quad \mathbf{H} = \text{rot}\mathbf{A}.$$

By the gauge invariance of the combined theory, the interaction between ψ and (φ, \mathbf{A}) is given by exchanging the usual derivatives ∂_α with the gauge covariant derivative D_α which is defined by:

$$D_\alpha = \partial_\alpha - ie\mathbf{A}_\alpha, \quad \mathbf{A}_\alpha = (-\varphi, A_1, A_2, A_3).$$

Thus from (2.1), we obtain the following Lagrangian:

$$L_0 = \frac{1}{2} \cdot \psi_t + ie\varphi\psi \cdot^2 - \cdot \nabla\psi - ie\mathbf{A}\psi \cdot^2 - m^2|\psi|^2 + W(\psi).$$

Moreover since the Lagrangian of \mathbf{E} and \mathbf{H} is described by

$$L_1 = \frac{1}{2} |\mathbf{E}|^2 - |\mathbf{H}|^2 = \frac{1}{2} |\nabla\varphi + \mathbf{A}_t|^2 - |\text{rot}\mathbf{A}|^2,$$

the total Lagrangian $L = L_0 + L_1$ is given by

$$L = \frac{1}{2} \cdot \psi_t + ie\varphi\psi \cdot^2 - \cdot \nabla\psi - ie\mathbf{A}\psi \cdot^2 - m^2|\psi|^2 + W(\psi) + \frac{1}{2} \cdot \nabla\varphi + \mathbf{A}_t \cdot^2 - \frac{1}{2} \cdot \text{rot}\mathbf{A} \cdot^2. \tag{2.2}$$

Computing the Euler-Lagrange equations for $(\psi, \mathbf{A}, \varphi)$, we can obtain System (1.1)-(1.3). Moreover since the electromagnetic current $\mathbf{J}^\mu = e \operatorname{Im}(\bar{\psi} D^\mu \psi)$ is conserved, we have the following conservation laws:

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^3} e \operatorname{Im}(\bar{\psi} \psi_t) + e^2 |\psi|^2 \varphi \, dx &= 0 \quad (\text{charge}), \\ \frac{d}{dt} \int_{\mathbb{R}^3} e \operatorname{Im}(\bar{\psi} \nabla \psi) - e^2 |\psi|^2 \mathbf{A} \, dx &= 0 \quad (\text{momentum}). \end{aligned}$$

We refer to [11] for more details.

Finally we derive the energy conservation law which we will use later on. To this aim, we multiply $\bar{\psi}_t$ by (1.1), integrate it over \mathbb{R}^3 and take the real part. Then we obtain

$$\begin{aligned} \int_{\mathbb{R}^3} \frac{\partial}{\partial t} \left[\frac{1}{2} |\psi_t|^2 + \frac{1}{2} |\nabla \psi|^2 + \frac{m^2}{2} |\psi|^2 - W(\psi) - e^2 |\varphi|^2 \operatorname{Re}(\psi \bar{\psi}_t) \right. \\ \left. + e^2 |\mathbf{A}|^2 \operatorname{Re}(\psi \bar{\psi}_t) - \operatorname{Im} \left(e \varphi_t \psi \bar{\psi}_t + 2e \bar{\psi}_t \nabla \psi \cdot \mathbf{A} + e \psi \bar{\psi}_t \operatorname{div} \mathbf{A} \right) \right] dx = 0. \end{aligned} \quad (2.3)$$

Next multiplying \mathbf{A}_t by (1.2), we also have

$$\int_{\mathbb{R}^3} \frac{\partial}{\partial t} \left[\frac{1}{2} |\mathbf{A}_t|^2 + \frac{1}{2} |\operatorname{rot} \mathbf{A}|^2 - e \operatorname{Im}(\bar{\psi} \nabla \psi) \cdot \mathbf{A} + e^2 |\psi|^2 \mathbf{A} \cdot \mathbf{A} + \nabla \varphi \cdot \mathbf{A} \right] dx = 0, \quad (2.4)$$

where we used the fact

$$\operatorname{rot} \mathbf{A} \cdot \operatorname{rot} \mathbf{A}_t = \operatorname{div}(\mathbf{A}_t \times \operatorname{rot} \mathbf{A}) + \mathbf{A}_t \cdot \nabla(\operatorname{div} \mathbf{A}) - \mathbf{A}_t \cdot \Delta \mathbf{A}.$$

Finally multiplying $-\varphi_t$ by (1.3), we get

$$\int_{\mathbb{R}^3} \frac{\partial}{\partial t} \left[-\frac{1}{2} |\nabla \varphi|^2 + e \operatorname{Im}(\psi \bar{\psi}_t) \varphi_t - e |\psi|^2 \varphi \varphi_t + \varphi_t \operatorname{div} \mathbf{A}_t \right] dx = 0. \quad (2.5)$$

Summing (2.3)-(2.5) up and applying the integration by parts, we obtain

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^3} \left[\frac{1}{2} |\psi_t|^2 + \frac{1}{2} |\nabla \psi|^2 + \frac{m^2}{2} |\psi|^2 - W(\psi) + \frac{1}{2} |\operatorname{rot} \mathbf{A}|^2 + \frac{1}{2} |\mathbf{A}_t|^2 - \frac{1}{2} |\nabla \varphi|^2 \right. \\ \left. - \frac{e^2}{2} |\varphi|^2 |\psi|^2 + \frac{1}{2} |\mathbf{A}|^2 |\psi|^2 + e \operatorname{Im}(\psi \nabla \bar{\psi}) \cdot \mathbf{A} + \nabla \varphi \cdot \mathbf{A}_t + \varphi \operatorname{div} \mathbf{A}_t \right] dx = 0. \end{aligned}$$

Using again (1.3), we derive the following energy conservation law:

$$\begin{aligned} 0 &= \frac{d}{dt} E(\psi, \mathbf{A}, \varphi)(t) \\ &= \int_{\mathbb{R}^3} \left[\frac{1}{2} |\psi_t + ie\varphi\psi|^2 + \frac{1}{2} |\nabla \psi - ie\mathbf{A}\psi|^2 + \frac{m^2}{2} |\psi|^2 - W(\psi) \right. \\ &\quad \left. + \frac{1}{2} |\operatorname{rot} \mathbf{A}|^2 + \frac{1}{2} |\mathbf{A}_t + \nabla \varphi|^2 \right] dx. \end{aligned} \quad (2.6)$$

(We can derive (2.6) by applying the Noether theorem to the Lagrangian L of (2.2). See [5] for this topics.)

3 Estimates for the elliptic part

In this section, we give several estimates for the elliptic equation:

$$-\Delta\varphi + e^2|\psi|^2\varphi = e \operatorname{Im}(\psi\bar{\psi}_t). \tag{3.1}$$

Throughout this section, we suppose that $\psi(t, \cdot)$ has a compact support for each $t \in [0, T]$ and $\psi \in C^\infty(0, T) \times \mathbb{R}^3$. The estimates for general ψ can be obtained by a density argument.

In order to obtain some estimates for φ_t , we differentiate (3.1) with respect to t to get

$$-\Delta\varphi_t + e^2|\psi|^2\varphi_t + 2e^2 \operatorname{Re}(\psi\bar{\psi}_t)\varphi = e \operatorname{Im}(\psi\bar{\psi}_{tt}). \tag{3.2}$$

Moreover, taking the complex conjugate of (1.1), multiplying the resulting equation by ψ and taking the imaginary part, we also have

$$\begin{aligned} \operatorname{Im}(\psi\bar{\psi}_{tt}) &= \operatorname{Im}(\psi\Delta\bar{\psi} + 2ie\psi\nabla\bar{\psi} \cdot \mathbf{A} + 2e \operatorname{Re}(\psi\bar{\psi}_t)\varphi + e|\psi|^2\varphi_t) \\ &= \operatorname{Im}(\operatorname{div}(\psi\nabla\bar{\psi}) + 2e \operatorname{Re}(\psi\nabla\bar{\psi}) \cdot \mathbf{A} + 2e \operatorname{Re}(\psi\bar{\psi}_t)\varphi + e|\psi|^2\varphi_t) \\ &= \operatorname{div}(\operatorname{Im}(\psi\nabla\bar{\psi}) + |\psi|^2\mathbf{A} + 2e \operatorname{Re}(\psi\bar{\psi}_t)\varphi + e|\psi|^2\varphi_t). \end{aligned} \tag{3.3}$$

Here, we have used the fact $\operatorname{div} \mathbf{A} = 0$. From (3.2) and (3.3), we obtain

$$-\Delta\varphi_t = e \operatorname{div}(\operatorname{Im}(\psi\nabla\bar{\psi}) + |\psi|^2\mathbf{A}). \tag{3.4}$$

In this setting, one can prove the following lemma.

Lemma 3.1. *Let φ be a solution of (3.1). Then for $m \in \mathbb{N}$ with $m \geq 2$, $\varphi(t, \cdot)$ satisfies the following estimates for each $t \in [0, T]$:*

- (i) $\|\nabla\varphi(t, \cdot)\|_{H^m(\mathbb{R}^3)} \leq \tilde{C}_1\|\psi_t(t, \cdot)\|_{H^m(\mathbb{R}^3)},$
- (ii) $\|\varphi(t, \cdot)\|_{L^\infty(\mathbb{R}^3)} \leq \tilde{C}_2\|\psi_t(t, \cdot)\|_{H^m(\mathbb{R}^3)},$
- (iii) $\|\varphi_t(t, \cdot)\|_{H^m(\mathbb{R}^3)} \leq \tilde{C}_3\|\psi(t, \cdot)\|_{H^m(\mathbb{R}^3)}^2.$

Here \tilde{C}_1 and \tilde{C}_2 are constants depending on $\|\psi\|_{H^{m+1}}, \|\psi_t\|_{H^m}$ only, and \tilde{C}_3 depends on $\|\psi\|_{H^{m+1}}, \|\psi_t\|_{H^m}$ and $\|\nabla\mathbf{A}\|_{H^m}$.

Proof. (i) Let s be a non-negative integer with $s \leq m$. First we apply D^s to (3.1) and take the L^2 -inner product with $D^s\varphi$. Using an integration by parts, we have

$$\|\nabla(D^s\varphi)\|_{L^2}^2 + e^2 \int_{\mathbb{R}^3} D^s(|\psi|^2\varphi)D^s\varphi \, dx = e \int_{\mathbb{R}^3} \operatorname{Im} D^s(\psi\bar{\psi}_t) D^s\varphi \, dx.$$

Now we observe by the Leibniz rule that

$$\begin{aligned} D^s(|\psi|^2\varphi)D^s\varphi &= 2 \sum_{|\beta|+|\gamma|=s} \binom{\beta}{\gamma} \operatorname{Re}(\psi D^\gamma\bar{\psi})D^{\beta-\gamma}\varphi D^s\varphi \\ &= 2|\psi|^2|D^s\varphi|^2 + 2 \sum_{|\beta|+|\gamma|=s, |\gamma|=0} \binom{\beta}{\gamma} \operatorname{Re}(\psi D^\gamma\bar{\psi})D^{\beta-\gamma}\varphi D^s\varphi. \end{aligned}$$

Thus one has

$$\begin{aligned}
 & \|\nabla(D^s \varphi)\|_{L^2}^2 + e^2 \int_{\mathbb{R}^3} |\psi|^2 |D^s \varphi|^2 dx \\
 & \leq C \sum_{|\theta|+|\nu|=s, |\nu|=0} \int_{\mathbb{R}^3} |\psi| |D^\nu \psi| |D^{\beta-\nu} \varphi| |D^s \varphi| dx \\
 & \quad + C \sum_{|\theta|+|\nu|=s} \int_{\mathbb{R}^3} |D^\nu \psi| |D^{\beta-\nu} \psi_t| |D^s \varphi| dx \\
 & \leq C \sum_{|\theta|+|\nu|=s, |\nu|=0} \|D^\nu \psi D^{\beta-\nu} \varphi\|_{L^2} \| \psi D^s \varphi \|_{L^2} \\
 & \quad + C \sum_{|\theta|+|\nu|=s} \|D^\nu \psi\|_{L^3} \|D^{\beta-\nu} \psi_t\|_{L^2} \|D^s \varphi\|_{L^6} \\
 & \leq C \sum_{|\theta|+|\nu|=s} \|D^\nu \psi D^{\beta-\nu} \varphi\|_{L^2}^2 + \frac{e^2}{2} \|\psi D^s \varphi\|_{L^2}^2 \\
 & \quad + C \sum_{|\theta|+|\nu|=s, |\nu|=0} \|D^{\beta-\nu} \psi\|_{L^2}^2 + \frac{1}{2} \|\nabla(D^s \varphi)\|_{L^2}^2 \\
 & \quad + C \sum_{|\theta|+|\nu|=s} \|D^\nu \psi\|_{L^3}^2 + \frac{1}{2} \|\psi_t\|_{L^2}^2
 \end{aligned}$$

By the Hölder and the Sobolev inequalities, it follows that

$$\begin{aligned}
 \sum_{|\theta|+|\nu|=s, |\nu|=0} \|D^\nu \psi D^{\beta-\nu} \varphi\|_{L^2}^2 & \leq \sum_{|\theta|+|\nu|=s, |\nu|=0} \|D^\nu \psi\|_{L^3}^2 \|D^{\beta-\nu} \varphi\|_{L^6}^2 \\
 & \leq C \sum_{|\theta|+|\nu|=s, |\nu|=0} \|D^\nu \psi\|_{H^1}^2 \|\nabla(D^{\beta-\nu} \varphi)\|_{L^2}^2 \\
 & \leq C \|\psi\|_{H^{s+1}}^2 \|\nabla \varphi\|_{H^{s-1}}^2, \\
 \sum_{|\theta|+|\nu|=s} \|D^\nu \psi\|_{L^3}^2 \|D^{\beta-\nu} \psi_t\|_{L^2}^2 & \leq C \|\psi\|_{H^{s+1}}^2 \|\psi_t\|_{H^s}^2
 \end{aligned}$$

from which we deduce

$$\|\nabla \varphi\|_{H^m}^2 \leq C \|\psi\|_{H^{m+1}}^2 \|\nabla \varphi\|_{H^{m-1}}^2 + \|\psi\|_{H^{m+1}}^2 \|\psi_t\|_{H^m}^2. \quad (3.5)$$

Next we multiply (3.1) by φ and integrate the resulting equation over \mathbb{R}^3 .

Using again an integration by parts, we get

$$\begin{aligned}
 \int_{\mathbb{R}^3} |\nabla \varphi|^2 dx + e^2 \int_{\mathbb{R}^3} |\psi|^2 |\varphi|^2 dx & \leq |e| \int_{\mathbb{R}^3} |\psi| |\psi_t| |\varphi| dx \\
 & \leq |e| \int_{\mathbb{R}^3} |\psi|^2 |\varphi|^2 dx + \frac{1}{2} \int_{\mathbb{R}^3} |\psi_t|^2 dx \\
 & \leq \frac{e^2}{2} \int_{\mathbb{R}^3} |\psi|^2 |\varphi|^2 dx + \frac{1}{2} \|\psi_t\|_{L^2(\mathbb{R}^3)}^2.
 \end{aligned}$$

This implies that $\|\nabla \varphi\|_{L^2} \leq C \|\psi_t\|_{L^2}$. Then by induction and by taking into account (3.5), one can see that (i) holds.

(ii) By the embedding $W^{1,6}(\mathbb{R}^3) \hookrightarrow L^\infty(\mathbb{R}^3)$, one has

$$\|\varphi\|_{L^\infty} \leq C \sum_{j=1}^3 \left\| \frac{\partial \varphi}{\partial x_j} \right\|_{L^6} + \|\varphi\|_{L^6} .$$

$$\left\| \frac{\partial^2 \varphi}{\partial x_j \partial x_k} \right\|_{L^2}$$

and the Sobolev inequality, it follows that

$$\leq C \|\Delta \varphi\|_{L^2}$$

Moreover by the Calderon-Zygmund inequality:

$$\|\varphi\|_{L^\infty} \leq C \sum_{j=1}^3 \left\| \frac{\partial \varphi}{\partial x_j} \right\|_{L^2} + \|\nabla \varphi\|_{L^2} \leq C \|\Delta \varphi\|_{L^2} + \|\nabla \varphi\|_{L^2} .$$

From (3.1), we derive

$$\begin{aligned} \|\varphi\|_{L^\infty} &\leq C \|\psi \psi_t\|_{L^2} + \|\psi\|_{L^2}^2 + \|\nabla \varphi\|_{L^2} \\ &\leq C \|\psi\|_{L^\infty} \|\psi_t\|_{L^2} + \|\psi\|_{L^3}^2 \|\varphi\|_{L^6} + \|\nabla \varphi\|_{L^2} . \end{aligned}$$

Since $H^m(\mathbb{R}^3) \hookrightarrow L^\infty(\mathbb{R}^3)$ for $m \geq 2$, it follows that $\|\psi\|_{L^\infty} \leq C \|\psi\|_{H^m}$. Thus from (i), we get

$$\|\varphi\|_{L^\infty} \leq C \|\psi\|_{H^m} \|\psi_t\|_{L^2} + \|\psi\|_{H^m}^2 \|\psi_t\|_{L^2} + \|\psi_t\|_{L^2} \leq \tilde{C} \|\psi_t\|_{L^2} .$$

This completes the proof of (ii).

To prove (iii), we first observe that (3.4) can be written under the form:

$$\varphi_t = (-\Delta)^{-\frac{1}{2}} (-\Delta)^{-1} \operatorname{div} \left(\operatorname{Im}(\psi \nabla \bar{\psi}) + |\psi|^2 \mathbf{A} \right) . \quad (3.6)$$

Now we recall the Hardy-Littlewood-Sobolev inequality (See [17], P. 119):

$$\|(-\Delta)^{-\frac{\nu}{2}} f\|_{L^q(\mathbb{R}^N)} \leq C \|f\|_{L^p(\mathbb{R}^N)}$$

for $0 < \nu < N$, $1 < p < q < \infty$ and $\frac{1}{q} = \frac{1}{p} - \frac{\nu}{N}$. Applying D^s to (3.6) and using the Hardy-Littlewood-Sobolev inequality with $N = 3$, $\nu = 1$, $p = \frac{6}{5}$ and $q = 2$, we get

$$\begin{aligned} \|D^s \varphi_t\|_{L^2} &\leq C \|(-\Delta)^{-\frac{1}{2}} \operatorname{div} \left(\operatorname{Im}(D^s(\psi \nabla \bar{\psi})) + D^s(|\psi|^2 \mathbf{A}) \right)\|_{L^{\frac{6}{5}}} \\ &\leq C \|D^s(\psi \nabla \bar{\psi})\|_{L^{\frac{6}{5}}} + \|D^s(|\psi|^2 \mathbf{A})\|_{L^{\frac{6}{5}}} . \end{aligned}$$

Furthermore, direct computations give

$$\begin{aligned} \|D^s(\psi \nabla \bar{\psi})\|_{L^{\frac{6}{5}}} &\leq C \sum_{|\beta|+|\gamma|=s} \|D^\gamma \psi D^{\beta-\gamma}(\nabla \bar{\psi})\|_{L^{\frac{6}{5}}} \\ &\leq C \sum_{|\beta|+|\gamma|=s} \|D^\gamma \psi\|_{L^3} \|D^{\beta-\gamma}(\nabla \bar{\psi})\|_{L^2} \\ &\leq C \sum_{|\beta|+|\gamma|=s} \|D^\gamma \psi\|_{H^1} \|D^{\beta-\gamma}(\nabla \bar{\psi})\|_{L^2} \\ &\leq C \|\psi\|_{H^s} \|\psi\|_{H^{s+1}}, \\ \|D^s(|\psi|^2 \mathbf{A})\|_{L^{\frac{6}{5}}} &\leq C \sum_{|\beta|+|\gamma|=s} \|D^\gamma(|\psi|^2) D^{\beta-\gamma} \mathbf{A}\|_{L^{\frac{6}{5}}} \\ &\leq C \sum_{|\beta|+|\gamma|=s} \|D^\gamma(|\psi|^2)\|_{L^{\frac{3}{2}}} \|D^{\beta-\gamma} \mathbf{A}\|_{L^6} \\ &\leq C \sum_{|\beta|+|\gamma|=s} \|\psi\|_{L^3} \|D^\gamma \psi\|_{L^2} \|\nabla(D^{\beta-\gamma} \mathbf{A})\|_{L^2} \\ &\leq C \|\psi\|_{H^1} \|\psi\|_{H^{s+1}} \|\nabla \mathbf{A}\|_{H^s}, \end{aligned}$$

from which we deduce that $\|\psi_t\|_{H^m} \leq \tilde{C} \|\psi\|_{H^m}$. □

Next let (ψ, \mathbf{A}) and $(\tilde{\psi}, \tilde{\mathbf{A}})$ be given such that

$$(\psi, \tilde{\psi}) \in C(0, T), H^1(\mathbb{R}^3)^2, (\psi_t, \tilde{\psi}_t) \in C(0, T), L^2(\mathbb{R}^3)^2,$$

$$(\nabla \mathbf{A}, \nabla \tilde{\mathbf{A}}) \in C(0, T), L^2(\mathbb{R}^3)^3$$

and consider the unique solution φ and $\tilde{\varphi}$ of (3.1) with ψ and $\tilde{\psi}$ respectively. In this context, one can prove the next lemma which provides estimates on $\varphi - \tilde{\varphi}$.

Lemma 3.2. For each $t \in [0, T]$, the following estimates hold :

- (i) $\|\nabla(\varphi - \tilde{\varphi})(t, \cdot)\|_{L^2(\mathbb{R}^3)} \leq \hat{C}_1 \|\psi - \tilde{\psi}\|_{H^1(\mathbb{R}^3)} + \|\psi_t - \tilde{\psi}_t\|_{L^2(\mathbb{R}^3)}$,
- (ii) $\|(\varphi - \tilde{\varphi})(t, \cdot)\|_{L^6(\mathbb{R}^3)} \leq \hat{C}_2 \|\psi - \tilde{\psi}\|_{H^1(\mathbb{R}^3)} + \|\psi_t - \tilde{\psi}_t\|_{L^2(\mathbb{R}^3)}$,
- (iii) $\|(\varphi_t - \tilde{\varphi}_t)(t, \cdot)\|_{L^2(\mathbb{R}^3)} \leq \hat{C}_3 \|\psi - \tilde{\psi}\|_{H^1(\mathbb{R}^3)} + \|\nabla(\mathbf{A} - \tilde{\mathbf{A}})\|_{L^2(\mathbb{R}^3)}$.

Here \hat{C}_1 and \hat{C}_2 are constants depending on $\|\psi\|_{H^1}$, $\|\psi_t\|_{L^2}$ only, and \hat{C}_3 depends on $\|\psi\|_{H^1}$, $\|\psi_t\|_{L^2}$ and $\|\nabla \mathbf{A}\|_{L^2}$.

Proof. The equation satisfied by the difference $\varphi - \tilde{\varphi}$ is

$$-\Delta(\varphi - \tilde{\varphi}) + e^2(|\psi|^2\varphi - |\tilde{\psi}|^2\tilde{\varphi}) = e \operatorname{Im}(\psi\bar{\psi}_t - \tilde{\psi}\bar{\tilde{\psi}}_t). \tag{3.7}$$

We observe that

$$(|\psi|^2\varphi - |\tilde{\psi}|^2\tilde{\varphi})(\varphi - \tilde{\varphi}) = |\psi\varphi - \tilde{\psi}\tilde{\varphi}|^2 + \varphi\tilde{\varphi}(\bar{\psi} - \bar{\tilde{\psi}})(\tilde{\psi} - \psi),$$

$$(\psi\bar{\psi}_t - \tilde{\psi}\bar{\tilde{\psi}}_t)(\varphi - \tilde{\varphi}) = (\bar{\psi}_t - \bar{\tilde{\psi}}_t)(\psi\varphi - \tilde{\psi}\tilde{\varphi}) + \varphi(\psi - \tilde{\psi})(\bar{\tilde{\psi}}_t - \bar{\psi}_t) + \bar{\psi}_t(\psi - \tilde{\psi})(\varphi - \tilde{\varphi}).$$

Thus multiplying (3.7) by $\varphi - \tilde{\varphi}$ and integrating the resulting equation over \mathbb{R}^3 , one gets

$$\int_{\mathbb{R}^3} |\nabla(\varphi - \tilde{\varphi})|^2 dx + e^2 \int_{\mathbb{R}^3} |\psi\varphi - \tilde{\psi}\tilde{\varphi}|^2 dx$$

$$\leq e^2 \int_{\mathbb{R}^3} |\varphi\tilde{\varphi}| |\psi - \tilde{\psi}|^2 dx + e \int_{\mathbb{R}^3} |\psi_t - \tilde{\psi}_t| |\psi\varphi - \tilde{\psi}\tilde{\varphi}| dx$$

$$+ e \int_{\mathbb{R}^3} |\varphi| |\psi - \tilde{\psi}| |\psi_t - \tilde{\psi}_t| dx + e \int_{\mathbb{R}^3} |\psi_t| |\psi - \tilde{\psi}| |\varphi - \tilde{\varphi}| dx$$

$$\leq C \|\varphi\|_{L^6} \|\tilde{\varphi}\|_{L^6} \|\psi - \tilde{\psi}\|_{L^3}^2 + \frac{e^2}{2} \|\psi_t - \tilde{\psi}_t\|_{L^2}^2 + \frac{e^2}{2} \int_{\mathbb{R}^3} |\psi\varphi - \tilde{\psi}\tilde{\varphi}|^2 dx$$

$$+ C \|\varphi\|_{L^6} \|\psi - \tilde{\psi}\|_{L^3} \|\psi_t - \tilde{\psi}_t\|_{L^2} + C \|\psi_t\|_{L^2} \|\psi - \tilde{\psi}\|_{L^3} \|\varphi - \tilde{\varphi}\|_{L^6}.$$

By Lemma 3.1, it follows that

$$\|\nabla(\varphi - \tilde{\varphi})\|_{L^2}^2 \leq C \|\psi_t\|_{L^2} \|\tilde{\psi}_t\|_{L^2} \|\psi - \tilde{\psi}\|_{H^1}^2 + \|\psi_t - \tilde{\psi}_t\|_{L^2}^2$$

$$+ \|\psi_t\|_{L^2} \|\psi - \tilde{\psi}\|_{H^1} \|\psi_t - \tilde{\psi}_t\|_{L^2} + \|\psi_t\|_{L^2}^2 \|\psi - \tilde{\psi}\|_{H^1}^2$$

$$= \hat{C} \|\psi - \tilde{\psi}\|_{H^1}^2 + \|\psi_t - \tilde{\psi}_t\|_{L^2}^2.$$

This completes the proof of (i), and (ii) follows from (i). We can also prove (iii) in a similar way as in Lemma 3.1. \square

4 Solvability of the Cauchy problem

In this section, we prove Theorem 1.1. The proof is divided into two steps. Firstly, we reduce the original system (1.1)-(1.3) to a symmetric hyperbolic system. Secondly, we adopt the energy method of [6] to obtain a unique local solution.

4.1 Reduction to the hyperbolic system

In this subsection, we rewrite System (1.1)-(1.3) into a hyperbolic form. First, in order to guarantee that the Coulomb condition holds for $t \in (0, T)$, we introduce the projection operator P on divergence free vector fields. More precisely, we define $P : L^2(\mathbb{R}^3)^3 \rightarrow L^2(\mathbb{R}^3)^3$ by $P = (-\Delta)^{-1} \text{rot rot}$. By direct computations, one can see that if $\text{div} \mathbf{A} = 0$, it follows that $P\mathbf{A} = \mathbf{A}$. Applying P on Equation (1.2), we obtain

$$Q\mathbf{A} = P \left(e \text{Im}(\bar{\psi} \nabla \psi) - e^2 |\psi|^2 \mathbf{A} \right). \quad (4.1)$$

It is easy to see that when the initial data $\mathbf{A}_{(0)}$ and $\mathbf{A}_{(1)}$ are divergence free, the Coulomb condition holds for all $t \in (0, T)$. Indeed putting $B = \text{div} \mathbf{A}$, one has from (4.1) that $Q B = 0$, $B(0, x) = 0$ and $B_t(0, x) = 0$. Thus it follows that $B \equiv 0$ for all $t > 0$.

Decomposing $\psi = \psi_1 + i\psi_2$ and $\mathbf{A} = (\psi_3, \psi_4, \psi_5)$ with $\psi_i : \mathbb{R} \times \mathbb{R}^3 \rightarrow \mathbb{R}$, System (1.1), (1.3), (4.1) is reduced to the following set of equations:

$$\begin{aligned} Q\psi_1 &= 2e\varphi(\psi_2)_t + e\varphi_t\psi_2 + e^2\varphi^2\psi_1 + 2e(\psi_2)_{x_1}\psi_3 + (\psi_2)_{x_2}\psi_4 + (\psi_2)_{x_3}\psi_5 \\ &\quad - e^2(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_1 - m^2\psi_1 + W(\psi), \\ Q\psi_2 &= -2e\varphi(\psi_1)_t - e\varphi_t\psi_1 + e^2\varphi^2\psi_2 - 2e(\psi_1)_{x_1}\psi_3 + (\psi_1)_{x_2}\psi_4 + (\psi_1)_{x_3}\psi_5 \\ &\quad - e^2(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_2 - m^2\psi_2 + W(\psi). \end{aligned}$$

$$\begin{aligned} Q\psi_3 &= e \sum_{k=1}^3 P_{1k} \left(\psi_1(\psi_2)_{x_k} - \psi_2(\psi_1)_{x_k} - e(\psi_2^2 - \psi_1^2)\psi_{2+k} \right), \\ Q\psi_4 &= e \sum_{k=1}^3 P_{2k} \left(\psi_1(\psi_2)_{x_k} - \psi_2(\psi_1)_{x_k} - e(\psi_1^2 + \psi_2^2)\psi_{2+k} \right), \\ Q\psi_5 &= e \sum_{k=1}^3 P_{3k} \left(\psi_1(\psi_2)_{x_k} - \psi_2(\psi_1)_{x_k} - e(\psi_1^2 + \psi_2^2)\psi_{2+k} \right). \end{aligned}$$

Here $P = (P_{jk})_{1 \leq j, k \leq 3}$, $P_{jk} : L^2(\mathbb{R}^3) \rightarrow L^2(\mathbb{R}^3)$ is a linear operator defined by

$$P_{jk} = \delta_{jk} + R_j R_k \quad (j, k = 1, 2, 3)$$

and $R_j : L^2(\mathbb{R}^3) \rightarrow L^2(\mathbb{R}^3)$ is the Riesz transform given by

$$R_j = \frac{\partial}{\partial x_j} (-\Delta)^{-\frac{1}{2}}.$$

By the Fourier transform, it follows that $u = \mathcal{R}^{-1} \int_{|\xi|}^{\xi} F[u]$ for $u \in L^2(\mathbb{R}^3)$ and $\xi \in \mathbb{R}^3$. This implies that R_j is bounded from $L^2(\mathbb{R}^3)$ to $L^2(\mathbb{R}^3)$ and hence so does P_{jk} .

Next we introduce $(\psi_i)_t = \psi_{i+5}$ ($i = 1, \dots, 5$) and write the equations satisfied by ψ_i ($i = 6, \dots, 10$)

$$\begin{aligned}
 (\psi_6)_t &= (\psi_1)_{tt} = \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_1)_{x_j} + 2e\varphi\psi_7 + e\varphi_t\psi_2 + e^2\varphi^2\psi_1 - m\psi_1 \\
 &\quad + W'(\psi) + 2e \sum_{j=1}^3 \frac{\partial \psi_2}{\partial x_j} \psi_{2+j} - e(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_1. \\
 (\psi_7)_t &= (\psi_2)_{tt} = \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_2)_{x_j} - 2e\varphi\psi_6 - e\varphi_t\psi_1 + e^2\varphi^2\psi_2 - m\psi_2 \\
 &\quad + W'(\psi) - 2e \sum_{j=1}^3 \frac{\partial \psi_1}{\partial x_j} \psi_{2+j} - e^2(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_2. \\
 (\psi_8)_t &= (\psi_3)_{tt} = \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_3)_{x_j} \\
 &\quad + e \sum_{k=1}^3 P_{1k} (\psi_1(\psi_2)_{x_k} - \psi_2(\psi_1)_{x_k}) - e(\psi_1^2 + \psi_2^2)\psi_{2+k}. \\
 (\psi_9)_t &= (\psi_4)_{tt} = \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_4)_{x_j} \\
 &\quad + e \sum_{k=1}^3 P_{2k} (\psi_1(\psi_2)_{x_k} - \psi_2(\psi_1)_{x_k}) - e(\psi_1^2 + \psi_2^2)\psi_{2+k}. \\
 (\psi_{10})_t &= (\psi_5)_{tt} = \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_5)_{x_j} \\
 &\quad + e \sum_{k=1}^3 P_{3k} (\psi_1(\psi_2)_{x_k} - \psi_2(\psi_1)_{x_k}) - e(\psi_1^2 + \psi_2^2)\psi_{2+k}.
 \end{aligned}$$

Finally we introduce $(\psi_1)_{x_1} = \psi_{11}$, $(\psi_1)_{x_2} = \psi_{12}$, \dots , $(\psi_5)_{x_3} = \psi_{25}$ so that the equations on ψ_6, \dots, ψ_{10} become

$$\begin{aligned}
 (\psi_6)_t &= \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_{10+j}) + 2e\varphi\psi_7 + e\varphi_t\psi_2 + e^2\varphi^2\psi_1 - m^2\psi_1 + W'(\psi) \\
 &\quad + 2e \sum_{j=1}^3 \psi_{13+j}\psi_{2+j} - e^2(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_1. \\
 (\psi_7)_t &= \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_{13+j}) - 2e\varphi\psi_6 - e\varphi_t\psi_1 + e^2\varphi^2\psi_2 - m^2\psi_2 + W'(\psi) \\
 &\quad - 2e \sum_{j=1}^3 \psi_{10+j}\psi_{2+j} - e^2(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_2. \\
 (\psi_8)_t &= \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_{16+j}) + e \sum_{k=1}^3 P_{1k} (\psi_{11}\psi_{13+k} - \psi_{12}\psi_{10+k}) - e(\psi_1^2 + \psi_2^2)\psi_{2+k}. \\
 (\psi_9)_t &= \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_{19+j}) + e \sum_{k=1}^3 P_{2k} (\psi_{11}\psi_{13+k} - \psi_{12}\psi_{10+k}) - e(\psi_1^2 + \psi_2^2)\psi_{2+k}. \\
 (\psi_{10})_t &= \sum_{j=1}^3 \frac{\partial}{\partial x_j} (\psi_{22+j}) + e \sum_{k=1}^3 P_{3k} (\psi_{11}\psi_{13+k} - \psi_{12}\psi_{10+k}) - e(\psi_1^2 + \psi_2^2)\psi_{2+k}.
 \end{aligned}$$

Pointing out that $(\psi_{11})_t = \frac{\partial}{\partial x_1} \psi_6$, $(\psi_{12})_t = \frac{\partial}{\partial x_2} \psi_6, \dots$ and $(\psi_{25})_t = \frac{\partial}{\partial x_3} \psi_{10}$ and defining $\mathbf{U} = {}^t(\psi_1, \dots, \psi_{25})$, we can see that System (1.1), (1.3), (4.1) can be written into the following symmetric hyperbolic form

$$\frac{\partial \mathbf{U}}{\partial t} = \sum_{j=1}^3 A_j \frac{\partial \mathbf{U}}{\partial x_j} + \mathbf{F}(\mathbf{U}, \varphi, \varphi_t). \quad (4.2)$$

Here A_j ($j = 1, 2, 3$) is a symmetric 25×25 matrix which is defined by

$$A_j = \begin{pmatrix} 6 & 7 & 8 & 9 & 10 & 10+j & 13+j & 16+j & 19+j & 22+j \\ | & & & & & & & & & | \\ 6 & | & & & & 1 & & & & | \\ 7 & | & & & & & 1 & & & | \\ 8 & | & & & & & & 1 & & | \\ 10 & & & & & & & & & 1 \\ 9 & | & & & & & & & 1 & | \\ 10+j & & 1 & & & & & & & | \\ 13+j & & & 1 & & & & & & | \\ 16+j & & & & 1 & & & & & | \\ 19+j & & & & & 1 & & & & | \\ 22+j & & & & & & 1 & & & | \end{pmatrix}$$

and the nonlinear term $\mathbf{F}(\mathbf{U}, \varphi, \varphi_t) = {}^t f_1, f_2, \dots, f_{25}$ is given by

$$\begin{aligned} f_i &= \psi_{5+i} \quad (i = 1, \dots, 5). \\ f_6 &= 2e\varphi\psi_7 + e\varphi_t\psi_2 + e^2\varphi^2\psi_1 - m^2\psi_1 + W(\psi) \\ &\quad + 2e \sum_{j=1}^3 \psi_{13+j}\psi_{2+j} - e^2(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_1. \\ f_7 &= -2e\varphi\psi_6 - e\varphi_t\psi_1 + e^2\varphi^2\psi_2 - m^2\psi_2 + W(\psi) \\ &\quad - 2e \sum_{j=1}^3 \psi_{10+j}\psi_{2+j} - e^2(\psi_3^2 + \psi_4^2 + \psi_5^2)\psi_2. \\ f_{7+j} &= e \sum_{k=1}^3 P_{jk} (\psi_1\psi_{13+k} - \psi_2\psi_{10+k}) - e(\psi_1^2 + \psi_2^2)\psi_{2+k} \quad (j = 1, 2, 3). \\ f_i &= 0 \quad (i = 11, \dots, 25). \end{aligned} \quad (4.3)$$

Moreover, by using the vector \mathbf{U} , Equation (3.1) can be rewritten as

$$-\Delta\varphi + e(\psi_1^2 + \psi_2^2)\varphi = e(\psi_1\psi_7 - \psi_2\psi_6). \quad (4.4)$$

To conclude this section, we write the final system derived from (1.1)-(1.3) as follows

$$\begin{cases} \frac{\partial \mathbf{U}}{\partial t} = \sum_{j=1}^3 A_j \frac{\partial \mathbf{U}}{\partial x_j} + \mathbf{F}(\mathbf{U}, \varphi, \varphi_t), \\ -\Delta\varphi + e^2(\psi_1^2 + \psi_2^2)\varphi = e(\psi_1\psi_7 - \psi_2\psi_6). \end{cases} \quad (4.5)$$

4.2 Unique existence of the solution for the Cauchy problem

In this subsection, we show that the hyperbolic system (4.2) has a unique solution in a suitable function space. To this aim, we argue as in [6]. Firstly we consider a *linearized version* of (4.2) and prove the existence of a unique solution by a standard energy method. Secondly, we study the corresponding solution map S and show that S is a contraction mapping on a suitable ball provided that T is sufficiently small. We will see below that this procedure gives the unique solution of (4.2).

To this end, for $m \in \mathbb{N}$ with $m \geq 2$, we suppose that

$$\begin{aligned} \psi_{(0)} &\in H^{m+1}(\mathbb{R}^3, \mathbb{C}), \quad \psi_{(1)} \in H^m(\mathbb{R}^3, \mathbb{C}), \\ \mathbf{A}_{(0)} &\in H^{m+1}(\mathbb{R}^3, \mathbb{R}^3) \text{ and } \mathbf{A}_{(1)} \in H^m(\mathbb{R}^3, \mathbb{R}^3) \end{aligned}$$

so that $\psi_{i(0)}$ ($i = 1, \dots, 25$) satisfy

$$\psi_{1(0)}, \psi_{2(0)}, \dots, \psi_{5(0)} \in H^{m+1}(\mathbb{R}^3), \quad \psi_{6(0)}, \psi_{7(0)}, \dots, \psi_{25(0)} \in H^m(\mathbb{R}^3).$$

Here we put

$$\begin{aligned} \psi_{(0)} &= \psi_{1(0)} + i\psi_{2(0)}, \quad \mathbf{A}_{(0)} = (\psi_{3(0)}, \psi_{4(0)}, \psi_{5(0)}), \\ \psi_{(1)} &= \psi_{6(0)} + i\psi_{7(0)}, \quad \mathbf{A}_{(1)} = (\psi_{8(0)}, \psi_{9(0)}, \psi_{10(0)}), \\ (\psi_{1(0)})_{x_1} &= \psi_{11(0)}, \quad (\psi_{1(0)})_{x_2} = \psi_{12(0)} \dots, \quad (\psi_{5(0)})_{x_3} = \psi_{25(0)}. \end{aligned}$$

We denote $X = H^{m+1}(\mathbb{R}^3)^5 \times H^m(\mathbb{R}^3)^{20}$ and $\mathbf{U}_{(0)} = {}^t(\psi_{1(0)}, \dots, \psi_{25(0)})$.

Take $\mathbf{U}_{(0)} \in X$ arbitrarily and put $R = 2 \sum_{i=1}^{25} \|\psi_{i(0)}\|_{H^m}$. For $T > 0$, we set

$$B_R := \left\{ \mathbf{U}(t, x) = {}^t \psi_i(t, x) \right\}_{i=1}^{25} \in C(0, T), X; \quad \sup_{t \in (0, T)} \|\psi_i(t, \cdot)\|_{H^m} \leq R.$$

We are going to find a solution of (4.2) by the following procedure. First for given $\mathbf{U} \in B_R$, we obtain φ by solving the elliptic equation (4.4). Next we define the space $Y_T = C(0, T), X$ and the mapping

$$S : Y_T \rightarrow Y_T; \quad S(\mathbf{U}) = \mathbf{V},$$

where \mathbf{V} is a unique solution of the following equation.

$$\begin{cases} \frac{\partial \mathbf{V}}{\partial t} = \sum_{j=1}^3 A_j \frac{\partial \mathbf{V}}{\partial x_j} + \mathbf{F}(\mathbf{U}, \varphi, \varphi_t), \\ \mathbf{V}(0, x) = \mathbf{U}_{(0)}(x). \end{cases} \quad (4.6)$$

Note that the existence of the solution \mathbf{V} to (4.6) is straightforward (see Lemma 4.4 for more details). The idea is then to apply a fixed point theorem to S by getting estimates on \mathbf{V} through the use of energy estimates.

To this end, we first apply Lemma 3.1 to obtain bounds on φ , which allows us to perform estimates on the nonlinear terms \mathbf{F} as it is proved in the next lemma.

Lemma 4.1. *Let $\mathbf{U} \in Y_T$ be given and φ be the corresponding solution of the elliptic equation (4.4). If $\mathbf{U} \in B_R$, then the nonlinear term $\mathbf{F} = {}^t(f_i)$ ($i = 1, \dots, 25$) defined in (4.3) satisfies*

$$\|f_i(\mathbf{U}, \varphi, \varphi_t)\|_{C((0, T), H^m)} \leq C(R),$$

where $C(R)$ is a constant depending only on R .

Proof. First we observe by the definition of $\mathbf{F} = {}^t(f_i)$ that

$$\|f_i\|_{H^m} = \|\psi_{5+i}\|_{H^m} \leq R \quad (i = 1, \dots, 5) \text{ and } \|f_i\|_{H^m} = 0 \quad (i = 11, \dots, 25).$$

Next we have

$$\|f_{7+j}\|_{H^m} \leq |e| \sum_{k=1}^3 \|P_{jk}\psi_1\psi_{13+k}\|_{H^m} + \|P_{jk}\psi_2\psi_{10+k}\|_{H^m} + \|eP_{jk}\psi_1^2\psi_{2+k}\|_{H^m} + \|eP_{jk}\psi_2^2\psi_{2+k}\|_{H^m} \quad (j = 1, 2, 3).$$

Since P_{jk} is a bounded operator from $L^2(\mathbb{R}^3)$ to $L^2(\mathbb{R}^3)$ and $H^m(\mathbb{R}^3)$ is a Banach algebra for $m \geq 2$, we get

$$\begin{aligned} \|P_{jk}\psi_1\psi_{13+k}\|_{H^m} &\leq C\|\psi_1\|_{H^m}\|\psi_{13+k}\|_{H^m} \leq CR_3^2, \\ \|P_{jk}\psi_1\psi_{2+k}\|_{H^m} &\leq C\|\psi_1\|_{H^m}\|\psi_{2+k}\|_{H^m} \leq CR. \end{aligned}$$

Thus one has

$$\|f_{7+j}\|_{H^m} \leq C(R^2 + R^3) \quad (j = 1, 2, 3).$$

Next by the definition of f_6 , it follows that

$$\begin{aligned} \|f_6\|_{H^m} &\leq C\|\varphi\psi_7\|_{H^m} + \|\varphi_t\psi_2\|_{H^m} + \|\varphi^2\psi_1\|_{H^m} + \|\psi_1\|_{H^m} \\ &\quad + \sum_{k=1}^3 \|\psi_{13+k}\psi_{2+k}\|_{H^m} + \|\psi^2\psi_1\|_{H^m} + \|W^j(\psi)\|_{H^m}. \end{aligned}$$

By Lemma 3.1, we have

$$\begin{aligned} \|\varphi\psi_7\|_{H^m} &= \sum_{s \leq m} \|D^s(\varphi\psi_7)\|_{L^2} \leq C \sum_{s \leq m} \sum_{|\theta|+|\gamma|=s} \|D^\gamma \varphi D^{\theta-\gamma} \psi_7\|_{L^2} \\ &= C \sum_{s \leq m} \sum_{|\theta|=s} \|\varphi D^\theta \psi_7\|_{L^2} + C \sum_{s \leq m} \sum_{|\theta|+|\gamma|=s, |\gamma|=0} \|D^\gamma \varphi D^{\theta-\gamma} \psi_7\|_{L^2} \\ &\leq C\|\varphi\|_{L^\infty} \|\psi_7\|_{H^m} + \|\nabla \varphi\|_{H^m} \|\psi_7\|_{H^m} \\ &\leq C\|\psi_t\|_{H^m} \|\psi_7\|_{H^m} \leq CR^2. \\ \|\varphi^2\psi_1\|_{H^m} &\leq C \sum_{s \leq m} \sum_{|\theta|=s} \|\varphi^2 D^\theta \psi_2\|_{L^2} + C \sum_{s \leq m} \sum_{|\theta|+|\gamma|=s, |\gamma|=0} \|\varphi D^\gamma \varphi D^{\theta-\gamma} \psi_2\|_{L^2} \\ &\leq C\|\varphi\|_{L^\infty} \|\psi_2\|_{H^m} + C\|\varphi\|_{L^\infty} \|\nabla \varphi\|_{H^m} \|\psi_2\|_{H^m} \\ &\leq C\|\psi_t\|_{H^m} \|\psi_2\|_{H^m} \leq CR, \\ \|\varphi_t\psi_2\|_{H^m} &\leq \|\varphi_t\|_{H^m} \|\psi_2\|_{H^m} \leq C\|\psi\|_{H^m} \|\psi_2\|_{H^m} \leq CR^2. \end{aligned}$$

Moreover from (A), we also have

$$\|W^j(\psi)\|_{H^m} \leq C\|\psi\|_{H^m} \leq CR.$$

(See [1, Proposition 2.2, p. 101].) Thus we obtain $\|f_6\|_{L^2} \leq C(R)$. In a similar way, one can show that $\|f_7\|_{L^2} \leq C(R)$. This completes the proof. \square

Lemma 4.2. Let $\mathbf{U}, \tilde{\mathbf{U}} \in Y_T$ be given and $\varphi, \tilde{\varphi}$ be the corresponding solution of the elliptic equation (4.4) respectively. If $\mathbf{U} \in B_R$ and $\tilde{\mathbf{U}} \in B_R$, then it follows that

$$\|\mathbf{F}(\mathbf{U}, \varphi, \varphi_t) - \mathbf{F}(\tilde{\mathbf{U}}, \tilde{\varphi}, \tilde{\varphi}_t)\|_{L^\infty((0,T),L^2)} \leq C(R)\|\mathbf{U} - \tilde{\mathbf{U}}\|_{L^\infty((0,T),L^2)}.$$

Proof. By Lemma 3.2 and from the continuous embedding $H^m(\mathbb{R}^3) \hookrightarrow L^\infty(\mathbb{R}^3)$ for $m \geq 2$, we can see that the claim follows. \square

Now we are ready to prove the existence of a unique solution to the Cauchy problem:

$$\begin{cases} \frac{\partial \mathbf{U}}{\partial t} = \sum_{j=1}^3 A_j \frac{\partial \mathbf{U}}{\partial x_j} + \mathbf{F}(\mathbf{U}, \varphi, \varphi_t), \\ \mathbf{U}(0, x) = \mathbf{U}_{(0)}(x) \end{cases} \quad (4.7)$$

coupled with the elliptic equation:

$$-\Delta \varphi + e(\psi_1^2 + \psi_2^2)\varphi = e(\psi_1\psi_7 - \psi_2\psi_6). \quad (4.8)$$

The proof consists of four lemmas.

Lemma 4.3. *Let $\mathbf{U} \in B_R$ be given. Then there exists a unique solution $\varphi = \varphi(\mathbf{U}) \in C(0, T), D^{1,2}(\mathbb{R}^3)$ of (4.8). Moreover φ satisfies the estimates of Lemmas 3.1 and 3.2.*

Proof. Suppose that $\psi_1, \psi_2 \in H^1(\mathbb{R}^3)$ and $\psi_6, \psi_7 \in L^2(\mathbb{R}^3)$. We define a bilinear form $A : D^{1,2}(\mathbb{R}^3) \times D^{1,2}(\mathbb{R}^3) \rightarrow \mathbb{R}$ by

$$A(u, v) := \int_{\mathbb{R}^3} \nabla u \cdot \nabla v + e^2(\psi_1^2 + \psi_2^2)uv \, dx.$$

Then by the Hölder and the Sobolev inequalities, one has

$$\begin{aligned} |A(u, v)| &\leq \|\nabla u\|_{L^2} \|\nabla v\|_{L^2} + |e|^2 \|\psi_1\|_{L^3}^2 + \|\psi_2\|_{L^3}^2 \|u\|_{L^6} \|v\|_{L^6} \\ &\leq C \|u\|_{D^{1,2}} \|v\|_{D^{1,2}}, \\ \|u\|_{D^{1,2}}^2 &\leq A(u, u). \end{aligned}$$

Moreover putting $g = e(\psi_1\psi_7 - \psi_2\psi_6)$, we also have

$$\begin{aligned} \|g\|_{L^{\frac{6}{5}}} &\leq C (\|\psi_1\|_{L^3} \|\psi_7\|_{L^2} + \|\psi_2\|_{L^3} \|\psi_6\|_{L^2}) \\ &\leq C (\|\psi_1\|_{H^1} \|\psi_7\|_{L^2} + \|\psi_2\|_{H^1} \|\psi_6\|_{L^2}). \end{aligned}$$

This implies that $g \in L^{\frac{6}{5}}(\mathbb{R}^3) \hookrightarrow (D^{1,2}(\mathbb{R}^3))^*$. Thus by the Lax-Milgram theorem, there exists a unique solution of $A(\varphi, v) = \langle g, v \rangle$ for all $v \in D^{1,2}$. \square

Next we consider the linearized version of (4.7):

$$\begin{cases} \frac{\partial \mathbf{V}}{\partial t} = \sum_{j=1}^3 A_j \frac{\partial \mathbf{V}}{\partial x_j} + \mathbf{F}(\mathbf{U}, \varphi, \varphi_t), \\ \mathbf{V}(0, x) = \mathbf{U}_{(0)}(x). \end{cases} \quad (4.9)$$

Lemma 4.4. *For given $\mathbf{U} \in B_R$, the Cauchy problem (4.9) has a unique solution $\mathbf{V} \in C(0, T), X$.*

Proof. The proof follows by the standard existence theory for the hyperbolic system. (We refer to [1, Proposition 1.2, P. 115] for the proof.) \square

Now by Lemmas 4.3-4.4, one can see that the mapping S is well defined.

Lemma 4.5. *For sufficiently small $T^* > 0$, one has $S(B_R) \subset B_R$. Furthermore, there exists $\kappa \in (0, 1)$ such that for any $\mathbf{U}, \tilde{\mathbf{U}} \in B_R$, one can write*

$$\|S(\mathbf{U}) - S(\tilde{\mathbf{U}})\|_{L^\infty((0, T^*), L^2)} \leq \kappa \|\mathbf{U} - \tilde{\mathbf{U}}\|_{L^\infty((0, T^*), L^2)}. \quad (4.10)$$

Proof. We apply the standard energy estimate method. To this aim, let s be a non-negative integer with $s \geq 2$. We apply D^s on (4.9) and take the L^2 -inner product with $D^s \mathbf{V}$ to obtain

$$\frac{\partial}{\partial t} \int_{\mathbb{R}^3} |D^s \mathbf{V}|^2 dx = \sum_{j=1}^3 \int_{\mathbb{R}^3} D^s A_j \frac{\partial \mathbf{V}}{\partial x^j} \cdot D^s \mathbf{V} dx + \int_{\mathbb{R}^3} D^s \mathbf{F} \cdot D^s \mathbf{V} dx.$$

Since A_j is symmetric and consists of constant elements, it follows that

$$\begin{aligned} \int_{\mathbb{R}^3} D^s A_j \frac{\partial \mathbf{V}}{\partial x^j} \cdot D^s \mathbf{V} dx &= \int_{\mathbb{R}^3} D^s A_j \frac{\partial}{\partial x^j} D^s \mathbf{V} \cdot D^s \mathbf{V} dx \\ &= \int_{\mathbb{R}^3} \frac{\partial}{\partial x^j} D^s \mathbf{V} \cdot (A_j D^s \mathbf{V}) dx \\ &= - \int_{\mathbb{R}^3} D^s \mathbf{V} \cdot \frac{\partial}{\partial x^j} (A_j D^s \mathbf{V}) dx \\ &= - \int_{\mathbb{R}^3} D^s \mathbf{V} \cdot D^s A_j \frac{\partial \mathbf{V}}{\partial x^j} dx, \end{aligned}$$

showing that

$$\int_{\mathbb{R}^3} D^s A_j \frac{\partial \mathbf{V}}{\partial x^j} \cdot D^s \mathbf{V} dx = 0.$$

As a consequence, we get

$$\frac{\partial}{\partial t} \frac{1}{2} \|D^s \mathbf{V}(t, \cdot)\|_{L^2}^2 \leq \|D^s \mathbf{F}\|_{L^2} \|D^s \mathbf{V}\|_{L^2} \leq \frac{1}{2} \|D^s \mathbf{V}(t, \cdot)\|_{L^2}^2 + \frac{1}{2} \|D^s \mathbf{F}\|_{L^2}^2.$$

Now we put $y(t) = \frac{1}{2} \|D^s \mathbf{V}(t, \cdot)\|_{L^2}^2$. By Lemma 4.1, one has

$$y'(t) \leq y(t) + C(R),$$

from which we deduce, by the Gronwall inequality, that

$$y(t) \leq y(0)e^t + C(R)(e^t - 1) \text{ for all } t \in (0, T).$$

Choosing $T^* > 0$ small enough, we derive

$$\begin{aligned} \sup_{t \in (0, T^*)} \|D^s \mathbf{V}(t, \cdot)\|_{L^2} &\leq \|D^s \mathbf{U}_{(0)}\|_{L^2} e^{T^*} + 2C(R)(e^{T^*} - 1)^{\frac{1}{2}} \\ &\leq \frac{R^2}{4} e^{T^*} + 2C(R)(e^{T^*} - 1)^{\frac{1}{2}} \leq R. \end{aligned}$$

This implies that $S(B_R) \subset B_R$.

Writing the equation satisfied by $\mathbf{V} - \tilde{\mathbf{V}}$ and arguing as above, one has

$$\frac{\partial}{\partial t} \frac{1}{2} \|(\mathbf{V} - \tilde{\mathbf{V}})(t, \cdot)\|_{L^2}^2 \leq \frac{1}{2} \|\mathbf{V} - \tilde{\mathbf{V}}\|_{L^2}^2 + \frac{1}{2} \|\mathbf{F}(\mathbf{U}, \varphi, \varphi_t) - \mathbf{F}(\tilde{\mathbf{U}}, \tilde{\varphi}, \tilde{\varphi}_t)\|_{L^2}^2$$

Again we put $z(t) = \frac{1}{2} \|(\mathbf{V} - \tilde{\mathbf{V}})(t, \cdot)\|_{L^2}^2$. Lemma 4.2 and the Gronwall inequality ensure that

$$z(t) \leq z(0)e^t + C\|\mathbf{U} - \tilde{\mathbf{U}}\|_{L^\infty((0, T), L^2)}^2 (e^t - 1)$$

Notice that $z(0) = \frac{1}{2} \|\mathbf{V}(0, \cdot) - \tilde{\mathbf{V}}(0, \cdot)\|_{L^2}^2 = \frac{1}{2} \|\mathbf{U}_{(0)} - \tilde{\mathbf{U}}_{(0)}\|_{L^2}^2 = 0$. Thus taking T^* smaller so that $\frac{C}{2C(R)(e^{T^*} - 1)} =: \kappa < 1$, we get

$$\|(\mathbf{V} - \tilde{\mathbf{V}})(t, \cdot)\|_{L^\infty((0, T^*), L^2)} \leq \kappa \|\mathbf{U} - \tilde{\mathbf{U}}(t, \cdot)\|_{L^\infty((0, T^*), L^2)}.$$

This completes the proof. \square

Now since S is a contraction mapping, there exists a unique $\mathbf{U} \in B_R$ such that $S(\mathbf{U}) = \mathbf{U}$. This implies that \mathbf{U} is a solution of (4.7).

Lemma 4.6. \mathbf{U} is the unique solution of (4.7).

Proof. The proof is a straightforward consequence of Estimate (4.10) and we omit the details. \square

Proof of Theorem 1.1. Let φ and $\mathbf{U} = (U_j)_{1 \leq j \leq 25}$ be the unique solution to Equations (4.4) and (4.7). We recall that $\varphi \in C(0, T), D^{1,2}(\mathbb{R}^3)$, $U_j \in C(0, T), H^{m+1}(\mathbb{R}^3)$ for all $j = 1, \dots, 5$ and $U_j \in C(0, T), H^m(\mathbb{R}^3)$ for $j = 6, \dots, 25$. Define $\tilde{\mathbf{U}} = (\tilde{U}_j)_{1 \leq j \leq 25}$ by

$$\begin{aligned} \tilde{U}_j &= U_j, \quad \tilde{U}_{j+5} = (U_j)_t \quad \text{for } j = 1, \dots, 5, \\ \tilde{U}_{11}, \tilde{U}_{12}, \tilde{U}_{13} &= \nabla U_1, \quad \tilde{U}_{14}, \tilde{U}_{15}, \tilde{U}_{16} = \nabla U_2, \\ \tilde{U}_{17}, \tilde{U}_{18}, \tilde{U}_{19} &= \nabla U_3, \quad \tilde{U}_{20}, \tilde{U}_{21}, \tilde{U}_{22} = \nabla U_4, \quad \tilde{U}_{23}, \tilde{U}_{24}, \tilde{U}_{25} = \nabla U_5. \end{aligned}$$

Then it is obvious that $\tilde{\mathbf{U}}$ satisfies the Cauchy Problem (4.9). By Estimate (4.10), one can write

$$\|(\mathbf{U} - \tilde{\mathbf{U}})(t, \cdot)\|_{L^\infty((0, T^*), L^2)} \leq \kappa \|(\mathbf{U} - \tilde{\mathbf{U}})(0, \cdot)\|_{L^\infty((0, T^*), L^2)} = 0.$$

which provides $\tilde{\mathbf{U}} = \mathbf{U}$. As a consequence, the functions

$$\psi = U_1 + iU_2, \quad \mathbf{A} = (U_3, U_4, U_5) \quad \text{and} \quad \varphi$$

are the unique solutions to System (1.1)-(1.3). Furthermore, noticing that

$$\begin{aligned} \psi_t &= U_6 + iU_7, \quad \nabla \psi = \nabla U_1 + i\nabla U_2, \\ \mathbf{A}_t &= (U_8, U_9, U_{10}) \quad \text{and} \quad \nabla \mathbf{A} = (\nabla U_3, \nabla U_4, \nabla U_5), \end{aligned}$$

one can prove that

$$\begin{aligned} \psi &\in C(0, T^*), H^{m+1} \cap C^1(0, T^*), H^m, \\ \mathbf{A} &\in C(0, T^*), H^{m+1} \cap C^1(0, T^*), \mathcal{H}^m, \\ \varphi &\in C(0, T), D^{1,2}(\mathbb{R}^3), \nabla \varphi \in \overset{\circ}{C}(0, T^*), H^m, \varphi_t \in C(0, T^*), H^m, \end{aligned}$$

which ends the proof of Theorem 1.1. \square

Remark 4.7. Note that it seems for the moment out of reach to solve the Cauchy Problem for System (1.1)-(1.3) in the energy space defined by

$$\begin{aligned} \psi &\in C(0, T), H^1(\mathbb{R}^3, \mathbb{C}) \cap C^1(0, T), L^2(\mathbb{R}^3, \mathbb{C}), \varphi \in C(0, T), D^{1,2}(\mathbb{R}^3, \mathbb{R}) \\ \mathbf{A} &\in C(\overset{\circ}{0}, T), D^{1,2}(\mathbb{R}^3, \mathbb{R}^3) \cap C^1(\overset{\circ}{0}, T), L^2(\mathbb{R}^3, \mathbb{R}^3). \end{aligned} \quad (4.11)$$

However, if we assume that W satisfies the condition:

(B) There exists $\mu \in (0, m^2)$ such that

$$\frac{m^2}{2} s^2 - W(s) \geq \frac{\mu}{2} s^2 \quad \text{for all } s \geq 0,$$

then one can prove the following result.

Proposition 4.8. Assume (A) and (B). Then there exists $C > 0$ such that

$$\sup_{t \in (0, T)} \|\psi(t, \cdot)\|_{H^1} + \|\psi_t(t, \cdot)\|_{L^2} + \|\nabla \mathbf{A}(t, \cdot)\|_{L^2} + \|\mathbf{A}_t(t, \cdot)\|_{L^2} \leq C.$$

Proof. First by the energy conservation law (2.6) and from (B), we have

$$\|\nabla \mathbf{A}\|_{L^2} \leq 2E(0), \quad \|\psi\|_{L^2} \leq \frac{2}{\mu}E(0),$$

$$\|\nabla \psi - ie\mathbf{A}\psi\|_{L^2} + \|\psi_t + ie\varphi\psi\|_{L^2} + \|\mathbf{A}_t + \nabla\varphi\|_{L^2} \leq 2E(0).$$

Now by the interpolation inequality, it follows that $\|\psi\|_{L^3} \leq \|\psi\|_{L^2}^{\frac{1}{2}}\|\psi\|_{L^6}^{\frac{1}{2}}$.

Then by the Sobolev and the triangular inequalities, we get

$$\begin{aligned} \|\psi\|_{L^3} &\leq C\|\nabla\psi\|_{L^2}^{\frac{1}{2}} \leq C\|\nabla\psi - ie\mathbf{A}\psi\|_{L^2} + \|e\mathbf{A}\psi\|_{L^2}^{\frac{1}{2}} \\ &\leq C(1 + \|\mathbf{A}\|_{L^6}\|\psi\|_{L^3})^{\frac{1}{2}} \leq C(1 + \|\nabla\mathbf{A}\|_{L^2}\|\psi\|_{L^3})^{\frac{1}{2}} \\ &\leq C(1 + \|\psi\|_{L^3})^{\frac{1}{2}} \leq \frac{C^2 + 1}{2} + \frac{1}{2}\|\psi\|_{L^3}. \end{aligned}$$

This implies that $\|\psi\|_{L^3} \leq C$ and hence $\|\nabla\psi\|_{L^2} \leq C$. Next we observe that (1.3) can be written as

$$-\Delta\varphi = e \operatorname{Im} \psi(\overline{\psi_t + ie\varphi\psi}) .$$

Multiplying this equation by φ and integrating over \mathbb{R}^3 , we obtain

$$\begin{aligned} \|\nabla\varphi\|_{L^2}^2 &\leq |e| \int_{\mathbb{R}^3} |\psi||\psi_t + ie\varphi\psi||\varphi| dx \\ &\leq |e|\|\psi\|_{L^3}\|\psi_t + ie\varphi\psi\|_{L^2}\|\varphi\|_{L^6} \leq C\|\nabla\varphi\|_{L^2}. \end{aligned}$$

This implies that $\|\nabla\varphi\|_{L^2} \leq C$. Finally by the triangular inequality, one has

$$\|\mathbf{A}_t\|_{L^2} \leq \|\mathbf{A}_t + \nabla\varphi\|_{L^2} + \|\nabla\varphi\|_{L^2} \leq C.$$

This completes the proof. □

Owing Proposition 4.8 and the conservation law (2.6), it is clear that every local solutions to (1.1)-(1.3) exists globally in time. To conclude, one can easily see that (B) implies that the potential term is positive and the cubic-quintic nonlinearity $W(s) = \frac{1}{3}s^3 - \frac{\lambda}{5}s^5$ satisfies (B) for large λ .

Acknowledgment

This paper was carried out while the second author was staying at the University of Bordeaux. The author is very grateful to all the staff of the University of Bordeaux for their kind hospitality. The second author is supported by JSPS Grant-in-Aid for Scientific Research (C) (No. 15K04970). Finally the authors would like to thank the referee for valuable comments.

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